GEOMETRIC PROPERTIES OF THE U-LINES IN TORIC COORDINATES $^{\scriptscriptstyle 1}$

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Abstract. Toric coordinates have been introduced in [1]. We explore some geometrical properties of its u-lines, such as finding the image of u-line by the Gauss map, finding the conjugated family, etc.

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1. Movement of a point onto an u-line

We remind the formulae of the toric coordinates:

(1)
$$\begin{vmatrix} x = (a + r\cos(u + v))\cos u \\ y = (a + r\cos(u + v))\sin u, & \rho = a + r\cos(u + v) \\ z = r\sin(u + v), & u, v \in [0, 2\pi]; & 0 < r < a \end{vmatrix} .$$

Let the vector equation of an *u*-line $C_r(u)$ be $\vec{r} = \vec{r}(u)$, r and v are constants (when we write in bold \mathbf{r} we mean the vector \vec{r}). Then the vector $\vec{r}''(u)$ is:

(2)
$$\begin{vmatrix} x = -a\cos u - 2r\cos(2u + v) \\ y = -a\sin u - 2r\sin(2u + v) \\ z = -r\sin(u + v) \end{vmatrix} .$$

Theorem 1.1. The vector $\vec{r} + \vec{r}''$ describes a circumference onto the plane xOy.

Proof. We must summarize (1) and (2), and to simplify the result. Then

(3)
$$\vec{r} + \vec{r}''$$
:
$$\begin{vmatrix} x = \frac{r}{2} \cos v - \frac{3}{2} r \cos(2u + v) \\ y = -\frac{r}{2} \sin v - \frac{3}{2} r \sin(2u + v) \\ z = 0 \end{vmatrix}$$
.

The last equation (3) represents a circumference K(v) with a center $D\left(\frac{r}{2}\cos v, -\frac{r}{2}\sin v\right)$ and a radius $\frac{3}{2}r$. The point M' runs two times through K when M runs once through $C_r(u)$. The initial point is $M'_0(-r\cos v, -2r\sin v)$, (u=0). We have a family of circumferences, when v varies from 0 to 2π . Its centers D make a phase torsion to an angle -v.

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Treating \mathbf{r}'' as an acceleration, we can find its tangent component. We have the scalar product

(4)
$$\mathbf{r}' \cdot \mathbf{r}'' = -r\sin(u+v) \cdot \rho.$$

Hence the tangent component of \mathbf{r}'' has the opposite sign to $\sin(u+v)$. If we take v=0 and $u\in[0,\pi]$, then the acceleration is minus and the speed decreases. When $u\in[\pi,2\pi]$ then the speed of M increases.

2. Image of an *u*-line by the Gauss map

The Gauss map Γ stands to each point M of the torus T - the point of the sphere, whose radius-vector is equal to the unit normal vector n(M) of T.

Let (1) are the coordinates of M, r=1 and $O_M(a\cos u, a\sin u, 0)$ be the center of the cross section of T. Then $n(M) = \overrightarrow{OM}$ has the following coordinates:

(5)
$$\left(\cos(u+v)\cos u, \cos(u+u)\sin u, \sin(u+v)\right).$$

The image of the *u*-line $C_1(v)$ consists of all points (5) on the sphere, when v = const. Let we denote this image by C'(v). The projection of the curve C'(v) onto xOy is a circumference

$$K: \left| \begin{array}{l} x = \cos(u+v)\cos u \\ y = \cos(u+v)\sin u \end{array} \right.$$

The circumferences K passes through O and has a radius $\frac{1}{2}$. The center of K is $O'\left(\frac{\cos v}{2},\,-\frac{\sin v}{2}\right)$. Particularly, when $v=0,\,O'\left(\frac{1}{2},\,0\right)$. Then O' turns round the origin to the angle -v: Thus we state the following theorem:

Theorem 2.1. The image $\Gamma(C_1(v))$ of every u-line is the Viviani's curve.

This image describes the upper part of the curve, when $0 \le u \le \pi$ and then goes to its lower part.

3. Differential-geometric properties of the u-lines

First, we represent the coefficients of the first and second quadratic form in toric coordinates (1). They are:

$$E=r^2+\rho^2,\quad G=F=1$$

$$L=-\Big(1+\cos(u+v)\Big)^2,\quad M=N=-1.$$

where $\rho = a + r \cos(u + v)$ is the distance of M to the axis Oz. We set $r \equiv 1$.

A. Normal curvature is an arbitrary point $M \in C(u)$. We must compute the angle φ between the tangent vector

$$\mathbf{t} = \mathbf{r}' \Big(-a\sin u - r\sin(2u + v), \ a\cos u + r\cos(2u + v), \ r\cos(u + v) \Big)$$

and the unit vector $\mathbf{e}_{\mathbf{p}}(-\sin u, \cos u)$ to the parallel at M. The scalar product

$$\mathbf{t.e_p} = a + r\cos(u + v) = \rho$$
 and $\cos\varphi = \frac{\rho}{\sqrt{r^2 + \rho^2}}$.

Then, by the Euler's formula, we get

$$k_n = k_1 \cos \varphi + k_2 \sin \varphi$$
.

The curvatures k_1 and k_2 satisfy the equation

$$\rho k^{2} - \left[\rho + \cos(u+v)\right]k + \cos(u+v) = 0.$$

So we obtain

(6)
$$k_1 = \frac{\cos(u+v)}{\rho}, \quad k_2 = 1, \quad k_n = \frac{r + \cos(u+v)}{\sqrt{r^2 + \rho^2}}.$$

B. The fundamental differential operator \mathcal{D} in a point $M \in C_1(u)$.

As we see, the Gauss map Γ maps an arbitrary point M, given by (1), to the point (5) of the sphere. The differential \mathcal{D} Γ is an isomorphism of the corresponding tangent spaces. We have

(7)
$$\mathscr{D}\Gamma(t) = \mathscr{D}\Gamma(\partial_u r) = \partial_u \vec{n} \quad \text{and} \quad \mathscr{D}\Gamma(\partial_u \vec{r}) = \partial_v \vec{n}$$

about the basic vectors. Therefore, when r=1

(8)
$$\partial_u \vec{n} = \left(-\sin(2u+v), \cos(2u+v), \cos(u+v) \right)$$
$$\partial_v \vec{r} = \partial_v \vec{n} = \left(-\sin(u+v)\cos u, -\sin(u+v)\sin u, \cos(u+v) \right) .$$

We can find the matrix $\mathcal D$ by a well-known formula

$$\mathscr{D} = \begin{pmatrix} k_1 & 0\\ 1 - k_1 & k_2 \end{pmatrix}, \text{ (see [1])},$$

where k_1 and k_2 are given by (6).

It could be directly verified that the linear transformation, given by this matrix, satisfies formulae (8). This means that \mathscr{D} is really the fundamental operator \mathscr{A} .

\mathbf{C} . Finding the conjugated family of the family of the u-lines.

For this aim we should find the differential equation of the family of u-lines. The coordinates of its tangent vector \mathbf{t} are (1,0).

If we denote by du and dv the coordinates of the conjugated direction, the following equation is verified

$$Lt_1 du + M(t_1 dv + t_2 du) + Nt_2 dv = 0.$$

In our case we obtain

(9)
$$-[1 + \cos(u+v)]^2 du - dv = 0.$$

In order to solve (9) we set u + v = U and we obtain the equation

$$(1 + \cos U)^2 dU = [(1 + \cos U)^2 - 1] dv,$$

which is an equation with separate variables. For the family of its integral curves we obtain that

(10)
$$\int \frac{(1+\cos U)^2}{2\cos U + \cos^2 U} dU = v + C.$$

This is the family of the conjugated lines of our u-lines.

References

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