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ON AN J-CONNECTION ON A B-MANIFOLD

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Let (M, g, J) be a Riemannian manifold M with a metric g and a structure J such that J^2 =-id, g(Jx, Jy)=-g(x, y), $x, y \in XM$, ∇J =0. Now we discuss another symmetric J-connection $\overline{\nabla}$, related with the connection ∇ of g. If \overline{R} =0, where \overline{R} is the curvature tensor of $\overline{\nabla}$ we get a known subclass [1], [3] of the B-manifolds. The inverse problem is discussed too.

A Riemannian manifold M_{2n} is in the class GB, of the so called generalized B-manifolds [2], if M_{2n} admits an almost complex structure J and a B-metric g, i.e.

$$J^2$$
=-id, $g(Jx, Jy)$ =- $g(x, y), x, y \in XM$.

If M is in GB and $\nabla J=0$, where ∇ is a Riemannian connection of g, then M is in the class B of the B-manifolds [4].

Let J_i^s and g_{is} be the local coordinates of J and g respectively. We note by $J_{ij}=J_i^s\underline{g}_{sj}$ and by virtue of (1) we have $J_{is}=J_{si}$. So we can define another symmetric connection $\overline{\nabla}$, whose Ricci-Christoffel symbols are as follows:

(2)
$$\overline{\Gamma}_{ij}^{k} = \Gamma_{ij}^{k} + T_{ij}^{k}, \quad T_{ij}^{k} = g_{ij}f^{k} - J_{ij} \tilde{f}^{k},$$

where f^k is a vector field, $\widetilde{f}^k = J_t^k f^t$ and Γ_{ij}^k are the Ricci-Christoffel symbols of ∇ . By a direct calculations we see, that $\overline{\nabla}$ is an *J*-connection (i.e. $\overline{\nabla}$ J=0), but it is not metric-connection (i.e. $\overline{\nabla}$ g \neq 0).

Now we consider the map $\alpha: \nabla \to \overline{\nabla}$ defined by (2). Let \overline{R} , R be the curvature tensor fields of $\overline{\nabla}$ and ∇ respectively. If T is the tensor of the affine deformation, then it is well known

(3)
$$\overline{R}_{ijk}^{h} = R_{ijk}^{h} + \nabla_{j} T_{ik}^{h} - \nabla_{k} T_{ij}^{h} + T_{ik}^{s} T_{sj}^{h} - T_{ij}^{s} T_{sk}^{h}$$

for the local coordinates of \overline{R} , R and T respectively. From (2) and (3) it follows

(4)
$$\overline{R}_{ijk}^{h} = R_{ijk}^{h} + g_{ik} P_{j}^{h} - g_{ij} P_{k}^{h} - J_{ik} \widetilde{P}_{j}^{h} + J_{ij} \widetilde{P}_{k}^{h},$$

$$\text{where } \mathtt{P}^{h}_{\ j} = \nabla f^{h} + f_{j}\,f^{h} - \quad \pmb{\widetilde{f}_{j}}\,\, \pmb{\widetilde{f}}^{\ h}\,, \qquad \pmb{\widetilde{P}}^{\ h}_{\ j} \ = \mathtt{P}^{t}_{\ j}\,\, J_{t}^{\ h}\,.$$

We note by $\overline{S}_{ij} = \overline{R}_{ijp}^p$, $S_{ij} = \mathbb{R}_{ijp}^p$ the local coordinates of corresponding Ricci tensors \overline{S} and S of $\overline{\nabla}$ and ∇ . The functions $\overline{\tau} = \overline{S}_{ij} \, g^{ij}$, $\overline{\tau}^* = \overline{S}_{ij} \, J^{ij}$ and $\tau = S_{ij} \, g^{ij}$, $\tau^* = S_{ij} \, J^{ij}$ are the first and the second scalar curvatures of $\overline{\nabla}$ and ∇ respectively.

After a long calculation from (4) we find

(5)
$$2(1-n)\overline{S}_{ij} = 2(1-n)S_{ij} + 4(1-n)P_{ji} - (\overline{\tau} - \tau)g_{ij} + (\overline{\tau}^* - \tau^*)J_{ij}$$

On the other hand we contract (4) by g^{ij} and using the above notations we set

(6)
$$\overline{S}_{ij} = S_{ij} + (2-2n)P_{ij}.$$

From (5) and (6) we get

(7)
$$4n(n-1)P_{ij} = (\tau - \overline{\tau})g_{ij} - (\overline{\tau}^* - \tau^*)J_{ij}$$

Theorem 1. The tensor field *Q* defined as follows

(8)
$$Q^{h}_{ijk} = R^{h}_{ijk} + \frac{\tau}{4n(1-n)} (g_{ij} \delta_{k}^{h} - g_{ik} \delta_{j}^{h} + J_{ik} J_{j}^{h} - J_{ij} J_{k}^{h}) - \frac{\tau^{*}}{4n(1-n)} (g_{ij} J_{k}^{h} - g_{ik} J_{j}^{h} - J_{ik} \delta_{j}^{h} + J_{ij} \delta_{k}^{h})$$

is invariant with respect to the map $\alpha: \nabla \to \overline{\nabla}$.

The proof follows from (4) and (7) immediately.

Now let \overline{V} be a locally flat connection. Then evidently $\overline{Q} = 0$ and from Theorem 1 it follows Q = 0. So (8) implies

$$\begin{split} \mathbb{R}(x,y,z,u) &= \frac{\tau}{4n(n-1)} \left[g(x,u)g(y,z) - g(x,Ju)g(y,Jz) - g(y,u)g(x,z) \right. \\ &+ g(y,Ju)g(x,Jz) \right] + \frac{\tau^*}{4n(n-1)} \left[g(x,Jz)g(y,u) + g(y,Ju)g(x,z) \right. \\ &- g(y,z)g(x,Ju) - g(y,Jz)g(x,u) \right]. \end{split}$$

Thus we have the following assertion.

Theorem 2. Let M_{2n} be in B and $\alpha: \nabla \to \overline{\nabla}$ defined by (2). If $\overline{\nabla}$ is locally flat, then M_{2n} satisfies the identity (9).

Moreover from (9) we obtain $S_{ij} = \frac{\tau}{2n} g_{ij} - \frac{\tau^*}{2n} J_{ij}$, i.e. M_{2n} is an almost Einstein manifold

The class of B-manifolds which satisfies (9) has been appeared at first in $[\ 1\]$ and further in $[\ 3\]$. In $[\ 1\]$ it has been proved that in this class the totally real section curvature is absolutely constant .

Now let have $\alpha: \nabla \to \overline{\nabla}$ defined by (2) but

$$\nabla_{i}f_{j} = \frac{\tau}{4n(n-1)} g_{ij} - \frac{\tau^{*}}{4n(n-1)} J_{ij} - f_{i} f_{j} + \widetilde{f}_{i} \widetilde{f}_{j},$$

$$\nabla_{i} \widetilde{f}_{j} = \frac{\tau}{4n(n-1)} J_{ij} + \frac{\tau^{*}}{4n(n-1)} g_{ij} - f_{i} \widetilde{f}_{j} - \widetilde{f}_{i} f_{j}.$$

Theorem 3. If ∇ satisfies (9) and f_n be a decision of (10), then $\overline{\nabla}$ is locally flat (n>2).

Proof. The integrability condition of (10) is satisfied identically by virtue of (9). So (10) has at least one solution. Then from (4), (7), (9) and (10) there follows \overline{R} =0, so the theorem is proved.

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