On almost paracontact Riemannian manifolds of type (n, n)

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Abstract. In this paper we give a classification with eleven basic classes of almost paracontact Riemannian manifolds of type (n, n) with respect to the covariant derivative of the (1, 1)-tensor of the almost paracontact structure.

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1. Introduction

In 1976 I. Sato [1] introduced the concepts of almost paracontact manifolds and of almost paracontact Riemannian manifolds as analogues of almost contact manifolds and of almost contact Riemannian manifolds.

After that S. Sasaki [2] defined the notion of an almost paracontact Riemannian manifold of type (p, q) and arbitrary dimension, where p and q are the numbers of the multiplicity of the structural eigenvalues 1 and -1, respectively. In addition, there is a simple eigenvalue 0.

In this paper we consider almost paracontact Riemannian manifolds of type (n, n), i.e. p = q = n. We put this fixation in view of reasons of later investigations relevant to 2n-dimensional Riemannian almost product manifolds (M^{2n}, P, g) with structural group $O(n) \times O(n)$, which are classified in [3]. In this reason the manifolds in our consideration could be construct by natural way as a direct product of (M^{2n}, P, g) and a real line or as a hypersurface of (M^{2n}, P, g) .

The method used in the present paper is analogous to the methods of classification in [4] and partly to those in [5] for the almost contact metric manifolds and for the almost contact manifolds with *B*-metric, respectively.

2. Preliminaries

A (2n+1)-dimensional real differentiable manifold M is said to have an almost paracontact structure (ϕ, ξ, η) of type (n, n), if it admits a (1, 1)-tensor ϕ , a vector field ξ and a 1-form η satisfying the following conditions:

$$\eta(\xi) = 1, \qquad \phi^2 = I_{2n+1} - \eta \otimes \xi, \qquad tr\phi = 0. \tag{1}$$

A positive definite Riemannian metric *g* is said to be compatible with the almost paracontact structure if it satisfies the following conditions

$$g(x,\xi) = \eta(x), \qquad g(\phi x, \phi y) = g(x, y) - \eta(x)\eta(y) \tag{2}$$

for all vectors x, y in the tangent space T_pM .

The quadruple (ϕ, ξ, η, g) of an almost paracontact structure of type (n, n) and a compatible metric is called an almost paracontact Riemannian structure of type (n, n).

We introduce the tensor \tilde{g} given by the equation

$$\tilde{g}(\cdot, \cdot) = g(\cdot, \phi \cdot) + \eta(\cdot)\eta(\cdot). \tag{3}$$

It is a compatible metric with the almost paracontact structure, too. The associated metric \tilde{g} to the Riemannian metric g is a pseudo-Riemannian metric of signature (n+1,n).

Let us denote the tensor of type (0, 3) by the equation

$$F(x, y, z) = g((\nabla_x \phi)y, z) \qquad (x, y, z \in T_p M). \tag{4}$$

Because of (1) and (2) the tensor F has the following properties

$$F(x, y, z) = F(x, z, y) = -F(x, \phi y, \phi z)$$

+ $\eta(y)F(x, \xi, z) + \eta(z)F(x, y, \xi)$ (5)

for all vectors x, y, z in T_pM .

If $\{e_i, \xi\}$ (i = 1, 2, ..., 2n) is a basis of the tangent space T_pM and g^{ij} are the components of the inverse matrix of g, then the following 1-forms are associated with the tensor F

$$\theta(x) = g^{ij} F(e_i, e_j, x), \quad \theta^*(x) = g^{ij} F(e_i, \phi e_j, x), \quad \omega(x) = F(\xi, \xi, x).$$
 (6)

for an arbitrary vector $x \in T_p M$.

3. The space of covariant derivatives of the (1, 1)-tensor of the almost paracontact structure

Let (V, ϕ, ξ, η, g) be (2n + 1)-dimensional vector space with almost paracontact Riemannian structure of type (n, n). We consider the vector space \mathcal{F} of the tensors of type (0, 3) over V having the properties (6). The metric g induces on \mathcal{F} an inner product \langle , \rangle , defined by

$$\langle F', F'' \rangle = g^{ip} g^{jq} g^{kr} F'(e_i, e_j, e_k) F''(e_p, e_q, e_r)$$

for arbitrary elements F', F'' in \mathcal{F} and a V's basis $\{e_i, e_{2n+1} = \xi\}$ (i = 1, 2, ..., 2n).

The standard representation of the structural group $O(n) \times O(n) \times I$ in V induces a natural representation of the structural group in \mathcal{F} :

$$(\lambda(a)F)(x, y, z) = F(a^{-1}x, a^{-1}y, a^{-1}z),$$

where $a \in O(n) \times O(n) \times I$, $F \in \mathcal{F}$, $x, y, z \in V$, so that

$$\langle \lambda(a)F', \lambda(a)F'' \rangle = \langle F', F'' \rangle.$$

We consider operators h, v, w on V with the properties

$$h^{2} = h, v^{2} = v, w^{2} = w,$$

$$h \circ v = v \circ h = h \circ w = w \circ h = v \circ w = w \circ v = 0.$$
(7)

The action of these operators on the space \mathcal{F} is represented by the equations

$$hF(x, y, z) = F(\phi^{2}x, \phi^{2}y, \phi^{2}z),$$

$$vF(X, Y, Z) = \eta(x)F(\xi, y, z) + \eta(y)F(x, z, \xi) + \eta(z)F(x, y, \xi)$$

$$-2\eta(x) [\eta(y)F(\xi, \xi, z) + \eta(z)F(\xi, \xi, y)],$$

$$wF(x, y, z) = \eta(x) [\eta(y)F(\xi, \xi, z) + \eta(z)F(\xi, \xi, y)]$$
(8)

The equality (8) implies

$$F = hF + vF + wF. (9)$$

Now we define basic operators $F_i: \mathcal{F} \to \mathcal{F} (i = 1, 2, ..., 10)$ by the equations:

$$F_{1}(F)(x, y, z) = \eta(x)F(\xi, y, z),$$

$$F_{2}(F)(x, y, z) = \eta(y)F(x, z, \xi) + \eta(z)F(x, y, \xi),$$

$$F_{3}(F)(x, y, z) = \eta(x)\left[\eta(y)F(\xi, \xi, z) + \eta(z)F(\xi, \xi, y)\right],$$

$$F_{4}(F)(x, y, z) = \eta(y)F(z, \xi, x) + \eta(z)F(y, \xi, x) -2\eta(y)\eta(z)F(\xi, \xi, x),$$

$$F_{5}(F)(x, y, z) = \eta(y)F(\phi x, \xi, \phi z) + \eta(z)F(\phi x, \xi, \phi y),$$

$$F_{6}(F)(x, y, z) = \eta(y)F(\phi z, \xi, \phi x) + \eta(z)F(\phi y, \xi, \phi x),$$

$$F_{7}(F)(x, y, z) = \frac{\theta(F)(\xi)}{2n}\left\{\eta(y)g(\phi x, \phi z) + \eta(z)g(\phi x, \phi y)\right\},$$

$$F_{8}(F)(x, y, z) = \frac{\theta^{*}(F)(\xi)}{2n}\left\{\eta(y)g(x, \phi z) + \eta(z)g(x, \phi y)\right\},$$

$$F_{9}(F)(x, y, z) = \frac{1}{2n}\left\{g(\phi x, \phi y)\theta(\phi^{2}z) + g(\phi x, \phi z)\theta(\phi^{2}y) - g(x, \phi y)\theta(\phi z) - g(x, \phi z)\theta(\phi y)\right\},$$

$$F_{10}(F)(x, y, z) = \frac{1}{3}\left\{hF(x, y, z) + hF(y, z, x) + hF(z, x, y)\right\}.$$

It is easy to check that $F_i(F) \in F$ for $F \in \mathcal{F}$ (i = 1, 2, ..., 10).

By necessity we have to compute the compositions of the basic operators and the associated 1-forms of $F_i(F)$.

LEMMA 1. Let $F \in \mathcal{F}$ and $F_{i,j}(F) = F_i(F_i(F))$ (i, j = 1, 2, ..., 10). Then we have:

By virtue of the operators F_i we construct new operators L_i (j = 1, 2, ..., 9). Let

$$L_1: \mathcal{F} \to \mathcal{F}, \qquad L_1(F) = F - 2F_3(F), \qquad F \in \mathcal{F}.$$

In a straightforward way using Lemma 1 we get that the operator L_1 is an involutive isometry on \mathcal{F} and commutes with the action of $O(n) \times O(n) \times I$. Hence L_1 has two eigenvalues +1 and -1, and the corresponding eigenspaces $(L_1\mathcal{F})^+$ and $(L_1\mathcal{F})^-$ are orthogonal and invariant mutually complementary subspaces of \mathcal{F} . Besides that, the components of F in the subspaces $(L_1\mathcal{F})^+$ and $(L_1\mathcal{F})^-$ are $\frac{1}{2}\{F + L_1(F)\}$ and $\frac{1}{2}\{F - L_1(F)\}$, respectively.

It is easy to show

LEMMA 2. If $F \in \mathcal{F}$ then

- a) $F_3(F) = 0$ iff $\omega(F) = 0$;
- b) $F \in (L_1 \mathcal{F})^+$, i.e. $L_1(F) = F$ iff $F_3(F) = 0$;
- c) $F \in (L_1 \mathcal{F})^-$, i.e. $L_1(F) = -F$ iff $F = F_3(F)$.

If we denote $\mathcal{F}_{11} = (L_1 \mathcal{F})^-$ and $\mathcal{F}_{11}^{\perp} = (L_1 \mathcal{F})^+$, then according Lemma 2 we have

$$\mathcal{F}_{11} = \{ F \in \mathcal{F} \mid F = F_3(F) \}, \qquad \mathcal{F}_{11}^{\perp} = \{ F \in \mathcal{F} \mid \omega(F) = 0 \}.$$

Thereby we obtain immediately

PROPOSITION 3. The decomposition $\mathcal{F} = \mathcal{F}_{11} \oplus \mathcal{F}_{11}^{\perp}$ is orthogonal and invariant with respect to the action of $O(n) \times O(n) \times I$. The component of an arbitrary element F in \mathcal{F}_{11} (respectively in \mathcal{F}_{11}^{\perp}) is $F_3(F)$ (respectively $F - F_3(F)$).

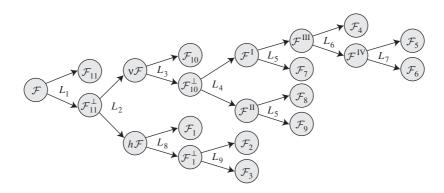


Figure 1

Using the same method we continue to decompose \mathcal{F} orthogonally and invariantly with respect to the action of $O(n) \times O(n) \times I$. Thereby we obtain the complete decomposition into irreducible components by the scheme of Figure 1.

The rest of operators L_j (j = 2, 3, ..., 9) we define by:

$$\begin{split} L_2(F) &= F - 2\{F_1(F) + F_2(F)\}, & L_6(F) &= F - 2F_7(F), \\ L_3(F) &= F_2(F) - F_1(F), & L_7(F) &= F - 2F_8(F), \\ L_4(F) &= -F_5(F), & L_8(F) &= F - 2F_9(F), \\ L_5(F) &= -F_4(F), & L_9(F) &= F - 2F_{10}(F). \end{split}$$

The operators L_j ($j=2,3,\ldots,9$) are involutive isometries on the corresponding subspaces and also commute with the action of $O(n)\times O(n)\times I$. According the applying method the corresponding eigenspaces of the eigenvalues +1 and -1 are orthogonal and mutually complementary subspaces of the reducible subspace of \mathcal{F} .

Since the endomorphism ϕ induces an almost product structure on the orthogonal complement $\{\xi\}^{\perp}$ of the subspace spanned by ξ and the restriction of g on $\{\xi\}^{\perp}$ is a Riemannian metric compatible with the almost product structure, then the decomposition of $h\mathcal{F}$ coincides with the known decomposition of the space of covariant derivatives of the traceless almost product structure [3].

Taking into account the above reasons we obtain

THEOREM 4. The decomposition $\mathcal{F} = \mathcal{F}_1 \oplus \mathcal{F}_2 \oplus \cdots \oplus \mathcal{F}_{11}$ is orthogonal and invariant with respect to the action of $O(n) \times O(n) \times I$. The characterization conditions of the factors \mathcal{F}_i (i = 1, 2, ..., 11) for arbitrary vectors x, y, z in V are:

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\mathcal{F}_1: F(x, y, z) = \frac{1}{2n} \{ g(\phi x, \phi y) \theta(\phi^2 z) + g(\phi x, \phi z) \theta(\phi^2 y) \}
                                     -g(x,\phi y)\theta(\phi z) - g(x,\phi z)\theta(\phi y)\};
             F(x, y, \phi z) + F(y, z, \phi x) + F(z, x, \phi y) = 0,
             F(\xi, y, z) = F(x, y, \xi) = 0, \quad \theta = 0;
 \mathcal{F}_3: F(x, y, z) + F(y, z, x) + F(z, x, y) = 0, F(\xi, y, z) = F(x, y, \xi) = 0;
 \mathcal{F}_{4}: \quad F(x, y, z) = \frac{\theta(\xi)}{2n} \{ g(\phi x, \phi y) \eta(z) + g(\phi x, \phi z) \eta(y) \};
\mathcal{F}_{5}: \quad F(x, y, z) = \frac{\theta^{*}(\xi)}{2n} \{ g(x, \phi y) \eta(z) + g(x, \phi z) \eta(y) \};
\mathcal{F}_{6}: \quad F(x, y, z) = \eta(y) F(z, \xi, x) + \eta(z) F(y, \xi, x) - 2\eta(y) \eta(z) F(\xi, \xi, x)
                               = \eta(y)F(\phi x, \xi, \phi z) + \eta(z)F(\phi x, \xi, \phi y), \quad \theta(\xi) = \theta^*(\xi) = 0;
 \mathcal{F}_7:
             F(x, y, z) = -\eta(y)F(z, \xi, x) - \eta(z)F(y, \xi, x) + 2\eta(y)\eta(z)F(\xi, \xi, x)
                               = \eta(y)F(\phi x, \xi, \phi z) + \eta(z)F(\phi x, \xi, \phi y);
             F(x, y, z) = \eta(y)F(z, \xi, x) + \eta(z)F(y, \xi, x) - 2\eta(y)\eta(z)F(\xi, \xi, x)
                               = -\eta(y)F(\phi x, \xi, \phi z) - \eta(z)F(\phi x, \xi, \phi y);
 \mathcal{F}_9:
             F(x, y, z) = -\eta(y)F(z, \xi, x) - \eta(z)F(y, \xi, x) + 2\eta(y)\eta(z)F(\xi, \xi, x)
                               = -\eta(y)F(\phi x, \xi, \phi z) - \eta(z)F(\phi x, \xi, \phi y);
\mathcal{F}_{10}:
             F(x, y, z) = \eta(x)F(\xi, y, z), \quad F(x, y, \xi) = 0;
             F(x, y, z) = \eta(x) \{ \eta(y)\omega(z) + \eta(z)\omega(y) \}.
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The components $p_i(F)$ of an arbitrary element F of \mathcal{F} in \mathcal{F}_i (i = 1, 2, ..., 11) are

$$\begin{aligned} p_1(F) &= F_9(F), & p_2(F) &= F_{10}(F), \\ p_3(F) &= hF - F_9(F) - F_{10}(F), & p_4(F) &= F_7(F), & p_5(F) &= F_8(F), \\ p_6(F) &= \frac{1}{4}\{F_2(F) - F_3(F) + F_4(F) + F_5(F) + F_6(F)\} - F_7(F) - F_8(F), \\ p_7(F) &= \frac{1}{4}\{F_2(F) - F_3(F) - F_4(F) + F_5(F) - F_6(F)\}, \\ p_8(F) &= \frac{1}{4}\{F_2(F) - F_3(F) + F_4(F) - F_5(F) - F_6(F)\}, \\ p_9(F) &= \frac{1}{4}\{F_2(F) - F_3(F) - F_4(F) - F_5(F) + F_6(F)\}, \\ p_{10}(F) &= F_1(F) - F_3(F), & p_{11}(F) &= F_3(F). \end{aligned}$$

4. Basic classes of almost paracontact Riemannian manifolds of type (n, n)

Let (M, ϕ, ξ, η, g) be almost paracontact Riemannian manifolds of type (n, n). The tangent space T_pM at an arbitrary point p in M is the vector space V equipped with an almost paracontact Riemannian structure of type (n, n). Then the corresponding vector space \mathcal{F} considered in the previous section has eleven orthogonal and invariant subspaces \mathcal{F}_i . In such a way the conditions for F at every point $p \in M$ give rise to the corresponding class of manifolds under consideration. Namely, an almost paracontact Riemannian manifold of type (n, n) is said to be in the class \mathcal{F}_i if the tensor F belongs to the subspace \mathcal{F}_i (i = 1, 2, ..., 11) over T_pM at every p in M. Thus the conditions define the eleven basic classes of almost paracontact Riemannian manifolds of type (n, n). Of course, the number of all classes of manifold under conversation is 2^{11} and their defining conditions are

easily obtainable by the basic ones. The special class \mathcal{F}_0 of almost paracontact Riemannian manifolds of type (n, n) is defined by the condition F = 0. This class belongs to each of the defined classes. It is an analogue to the class of cosymplectic almost contact metric manifolds [4] and to the respective class \mathcal{F}_0 in the classification of almost contact manifolds with B-metric [5].

The defined class \mathcal{F}_4 contains paracontact Riemannian manifolds of type (n, n) [1] and in particular para-Sasakian manifolds of type (n, n) [7].

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